

Some thoughts on the evolution of global flood forecasting

Dennis P. Lettenmaier

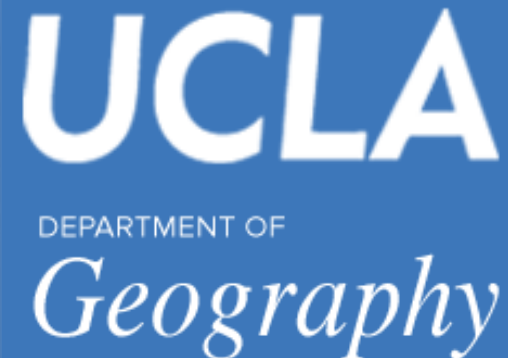
Department of Geography

University of California, Los Angeles

Global Flood Partnership Conference 2019

Guangzhou, China

June 12, 2019



Distinction between flood *prediction* and flood *forecasting*

Forecasting is for a particular (lead) time, whereas prediction is not. Hence, we forecast the river stage at noon on say June 12, but we predict the 100-year flood. So ECMWF is ECMWF rather than ECMWP (but then, what about NCEP?)

In any event, this talk focuses on *forecasting*

Outline

- 1) Flood forecast protocols in the developed world
(focus on U.S.)
- 2) Special challenges in the developing world
(where GFP is most needed)
- 3) Where are the gaps, and how can they be closed?

Flood forecast protocols in the developed world

Three lead times for flood forecasting

T1: precipitation forecast lead time

T2: time for precipitation incident on a watershed to reach the channel system

T3: time for water to move through the channel system to the forecast point

for flood forecast lead time τ :

$T < T_3$ need channel routing only PATH 1

**$T_3 < T < T_2 + T_3$ need hydrologic forecast and channel routing
PATH 2**

**$T > T_1 + T_2 + T_3$ need channel routing, hydrologic forecast,
and precipitation forecast PATH 3**

Forecast assets in the U.S. (arguably typical of developed countries)

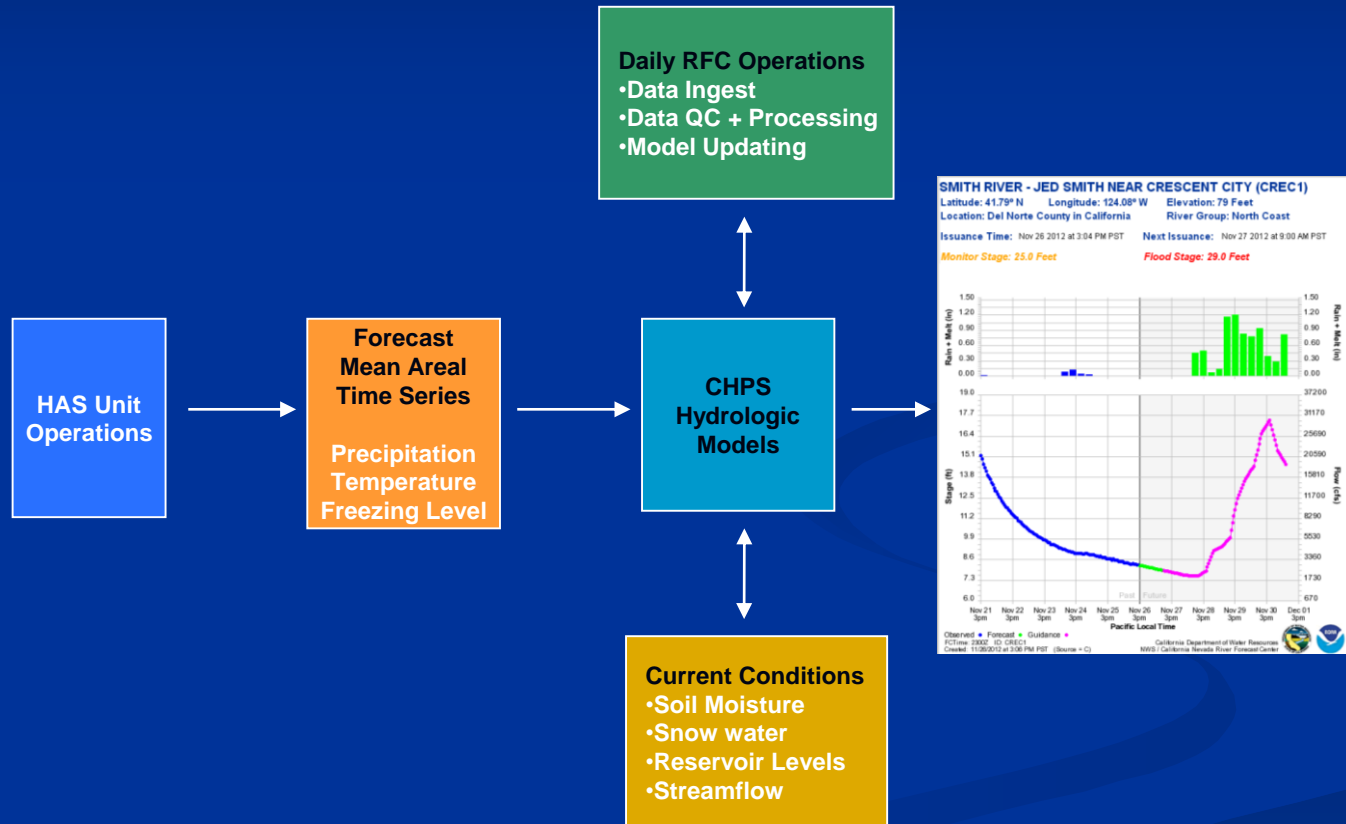
- 1) Stream gauge network (USGS operates ~8000-9000 gauges, 80-90% in real time, of these ~3500 are NWS real-time forecast points (provide both discharge and stage)
- 2) Precipitation observations – most of CONUS “flatlands” have precipitation radar coverage, plus several thousand precipitation gauges report in real-time
- 3) Detailed flood plain topographic data (Lidar in many cases)
- 4) Precipitation forecasts (from global and regional models)
- 5) Calibrated flood forecast model(s) using historical data from 1) and 2) that predict discharge at (upstream) forecast points
- 6) Calibrated channel routing algorithm(s) that predict discharge at downstream forecast points (and perhaps river stage) given discharge at upstream points

Chehalis River basin, Washington with USGS real-time stream discharge stations





Processing Deterministic Streamflow Prediction



Flood forecast example,
Russian River (CA) near
Guerneville, December
2005. Blue: observed
discharge, green:
forecast discharge 8 AM
Dec 26

RUSSIAN RIVER - GUERNEVILLE (GUEC1)

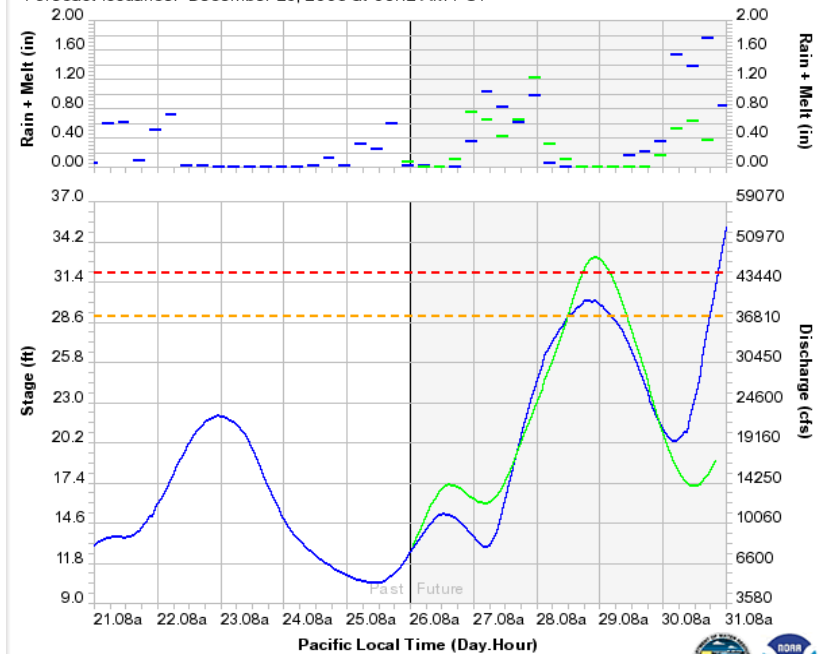
Latitude: 38.50° N Longitude: 123.00° W Elevation: 65 Feet
Location: Sonoma County in California

Forecast  Observed 

Previous Forecast	Next Forecast
Monday 12/26/2005 06-12 UTC	Monday 12/26/2005 18-00 UTC
Selected Date: Monday 12/26/2005 12:18 UTC	

GUEC1 - RUSSIAN - GUERNEVILLE BRIDGE (MS: 29.0 / FS: 32.0)

Forecast Issuance: December 26, 2005 at 08:12 AM PST



Observed  Forecast  Monitor  Flood 
Generated 07/18/2008 at 10:11 AM PDT

California Department of Water Resources
NWS / California Nevada River Forecast Center



Verification - Historical Graphical RVF

Month: Dec Day: 26 Year: 2005 Cycle: 12z-18z [Fetch](#)

To view other verification locations, use our [Historical Graphical River Forecast Interface](#)

The approach is highly dependent on a) real-time streamflow data, and b) high quality (in situ or radar) model forcings, especially precipitation (note that NSW uses mean areal (not spatially distributed) precipitation

Special challenges in the developing world (where GFP is most needed)

- Little or no stream gauge data (esp. real-time)
- Precipitation data limited to (generally lower quality) satellite or NWP analysis fields* (other forcing variables can come from NWP)

*not clear which is preferred

What hydrologic data do we have?

- Mostly inundation extent (and low quality DEM from which depths might be derived)
- Some altimetry (very large rivers) – mostly retrospective

[illegible]

Blue: Reference Water (permanent water bodies).

Visuals courtesy
Dartmouth Flood
Observatory

Where are the gaps, and how
can they be closed?

Near-term opportunities

- More surface extent data (lots of satellites, accessibility in near real-time issues, and mostly visible, hence cloud cover issues)
- Combine inundation extent with higher quality DEMs to get inundation depth (both real-time and retrospective opportunities)
- Faster processing of SAR data (avoids cloud cover issues)
- More attention to “Path 1” forecasts (needs retrospective analysis)

Longer term opportunities:

SWOT (Surface Water and Ocean Topography Mission, planned launch 2021) and NISAR (also 2021) will give us:

- **Channel cross-section estimates (via combination of multiple overpasses) down to low water (assume geometry, e.g., parabolic below that level)**
- **Inundation extent (snapshots) and water surface topography (including slope)**
- **Mostly retrospective (overpass ~10.5 days) except opportunistically**
- **But – could use SWOT archive to develop relationships between near-real time surface extent imagery (other sources) and water surface depths to improve hydrodynamic models**

Summary

- 1) Global flood forecasting is a compelling problem, and work over the last ~10 years has shown that it's feasible with current observational and modeling assets
- 2) The challenge now is to go from maps of inundation ("hit/miss") to quantitative predictions of flood depths, durations, and timing
- 3) Better and more creative exploitation of existing assets (both modeling and observational) in addition to new observations (mostly remote sensing) should lead to progress.